

Vector Calculus | Multivariate Calculus • Math 2210

Definitions

Gradient	Divergence	Curl	Jacobian
$F : \mathbb{R}^n \rightarrow \mathbb{R}$ $\nabla f(x, y, z)$ $= \frac{\partial f}{\partial x} \mathbf{i} + \frac{\partial f}{\partial y} \mathbf{j} + \frac{\partial f}{\partial z} \mathbf{k}$	$F = \langle P, Q, R \rangle$ $F : \mathbb{R}^3 \rightarrow \mathbb{R}^3$ $\text{div } \mathbf{F} = P_x + Q_y + R_z$ $= \frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y} + \frac{\partial R}{\partial z}$	$F = \langle P, Q, R \rangle$ $F : \mathbb{R}^3 \rightarrow \mathbb{R}^3$ $\text{curl } \mathbf{F} = (R_y - Q_z)\mathbf{i} + (P_z - R_x)\mathbf{j} + (Q_x - P_y)\mathbf{k}$	$\frac{\partial(x,y)}{\partial(u,v)} = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{vmatrix}$ $\frac{\partial(x,y,z)}{\partial(u,v,w)} = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} & \frac{\partial x}{\partial w} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} & \frac{\partial y}{\partial w} \\ \frac{\partial z}{\partial u} & \frac{\partial z}{\partial v} & \frac{\partial z}{\partial w} \end{vmatrix}$

Work, Flux and Circulation

Work	Flux	Circulation
$\int_C \mathbf{F} \cdot \mathbf{T} \, ds = \int_a^b \mathbf{F}(\mathbf{r}(t)) \cdot \mathbf{r}'(t) \, dt$	$\int_C \mathbf{F} \cdot \mathbf{N} \, ds = \int_a^b \mathbf{F}(\mathbf{r}(t)) \cdot \mathbf{n}(t) \, dt$ where $\mathbf{N} = \frac{\mathbf{n}(t)}{\ \mathbf{n}(t)\ }$, $\mathbf{n}(t) = \langle y'(t), -x'(t) \rangle$	$\oint_C \mathbf{F} \cdot \mathbf{T} \, ds$ \mathbf{T} is a unit vector wrt arc length

Fundamental Theorem of Line Integrals

Description	Theorem
Simplifies line integrals to evaluating the potential function f at the endpoints and subtracting. The curve is parameterized by $\mathbf{r}(t)$ where $\mathbf{r}(a)$ is initial and $\mathbf{r}(b)$ is final.	$\int_C \nabla f \cdot d\mathbf{r} = f(\mathbf{r}(b)) - f(\mathbf{r}(a))$

Potential Functions

$\mathbf{F}(x, y) = \langle P(x, y), Q(x, y) \rangle$ A vector field is conservative if it has a potential function.	How to find one: 1: $\int P(x, y) dx = g(x, y) + h(y)$ 2: $\frac{\partial}{\partial y}(g(x, y) + h(y)) = g_y(x, y) + h'(y)$	3: $g_x(x, y) + h'(y) = Q(x, y)$ 4: $\int h'(y) dy = h(y)$ 5: $f(x, y) = g(x, y) + h(y) + c$
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Green's and Stoke's Theorems

Description	Theorems
Green's Thm. converts the circulation of a vector field $F = \langle P, Q \rangle$ along a simple closed curve C to a double integral over region D . Stoke's Thm. is a generalized Green's Thm. not bounded to a plane. $\mathbf{r}(t)$ parametrizes C (boundary of S) and \mathbf{N} is a unit normal vector to the surface.	Green's Circulation: $\oint_C \mathbf{F} \cdot d\mathbf{r} = \iint_D (Q_x - P_y) \, dA = \iint_D \text{curl } \mathbf{F} \, dA$ Green's Flux: $\oint_C \mathbf{F} \cdot \mathbf{N} \, ds = \iint_D (P_x + Q_y) \, dA = \iint_D \text{div } \mathbf{F} \, dA$ Stoke's Theorem: $\int_C \mathbf{F} \cdot d\mathbf{r} = \iint_S \text{curl } \mathbf{F} \cdot d\mathbf{S}$

Divergence Theorem

Description	Theorem
Transforms difficult surface integral over S into a triple integral over solid E using the divergence of vector field F . Bounds are usually found with change of coordinates.	$\iiint_E \text{div } \mathbf{F} \, dV = \iint_S \mathbf{F} \cdot d\mathbf{S}$

Applications

Optimization

Second Derivative Test	Lagrange Multipliers
$D = f_{xx}(x_0, y_0)f_{yy}(x_0, y_0) - (f_{xy}(x_0, y_0))^2$ • If $D > 0$ and $f_{xx}(x_0, y_0) > 0$, (x_0, y_0) is a local min • If $D > 0$ and $f_{xx}(x_0, y_0) < 0$, (x_0, y_0) is a local max • If $D < 0$, (x_0, y_0) is a saddle point • If $D = 0$, test is inconclusive Critical Points: (x_0, y_0) is a critical point on $z = f(x, y)$ if $f_x(x_0, y_0) = f_y(x_0, y_0) = 0$ or either $f_x(x_0, y_0)$ or $f_y(x_0, y_0)$ DNE.	Optimize $f(x, y, z)$ subject to constraint $g(x, y, z) = k$ $\nabla f(x, y, z) = \lambda \nabla g(x, y, z)$ so $f_x = \lambda g_x, f_y = \lambda g_y, f_z = \lambda g_z$ Solve system of equations, substitute solutions into $f(x, y, z)$, and identify minimum, maximum (need existence and $\nabla g(x, y, z) \neq 0$)

Mass and Moments for Surfaces and Solids

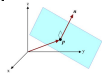
Mass	Moments	Moments of Inertia
Object Q with density function $\rho(x, y, z)$ $M = \iiint_Q \rho(x, y, z) \, dV$ Center of Mass: $(\bar{x} = \frac{M_{yz}}{m}, \bar{y} = \frac{M_{xz}}{m}, \bar{z} = \frac{M_{xy}}{m})$ Area and Volume: $A = \iint_A 1 \, dA \quad V = \iiint_Q 1 \, dV$	Two Dimensions $M_x = \iint_R y\rho(x, y) \, dA$ $M_y = \iint_R x\rho(x, y) \, dA$ Three Dimensions $M_{xy} = \iiint_Q z\rho(x, y, z) \, dV$ $M_{xz} = \iiint_Q y\rho(x, y, z) \, dV$ $M_{yz} = \iiint_Q x\rho(x, y, z) \, dV$	Two Dimensions $I_x = \iint_R y^2\rho(x, y) \, dA$ $I_y = \iint_R x^2\rho(x, y) \, dA$ Three Dimensions $I_x = \iiint_Q (y^2 + z^2)\rho(x, y, z) \, dV$ $I_y = \iiint_Q (x^2 + z^2)\rho(x, y, z) \, dV$ $I_z = \iiint_Q (x^2 + y^2)\rho(x, y, z) \, dV$

Common Shapes and Parameterizations


Conversion of Coordinates

Polar	Cylindrical	Spherical
$x = r \cos \theta, y = r \sin \theta$ $r^2 = x^2 + y^2, \tan \theta = \frac{y}{x}$ $dA = r \, dr \, d\theta$	$x = r \cos \theta, y = r \sin \theta$ $r^2 = x^2 + y^2, z = z, \tan \theta = \frac{y}{x}$ $dV = r \, dz \, dr \, d\theta$	$x = \rho \sin \phi \cos \theta, y = \rho \sin \phi \sin \theta$ $z = \rho \cos \phi, \rho^2 = x^2 + y^2 + z^2$ $dV = \rho^2 \sin \phi \, d\rho \, d\theta \, d\phi$


Plane

Image	Cartesian Form	Cylindrical Parameterization
	$Ax + By + Cz = D$ $\vec{N} = \langle A, B, C \rangle$	$x = r \cos \theta \quad y = r \sin \theta$ $z = D - Ar \cos \theta - Br \sin \theta \quad 0 < \theta < 2\pi$


Ellipsoid

Image	Cartesian Form	Spherical Parameterization
	$\frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} = 1$	$x = a \sin \phi \cos \theta \quad y = b \sin \phi \sin \theta \quad z = c \cos \phi$ $0 < \phi < \pi, 0 < \theta < 2\pi$


Elliptic Cone

Image	Cartesian Form	Cylindrical Parameterization
	$\frac{x^2}{a^2} + \frac{y^2}{b^2} - \frac{z^2}{c^2} = 0$	$x = ar \cos \theta \quad y = br \sin \theta \quad z = cr$ $0 \leq r < \infty, 0 < \theta < 2\pi$


Hyperboloid of One Sheet

Image	Cartesian Form	Cylindrical Parameterization
	$\frac{x^2}{a^2} + \frac{y^2}{b^2} - \frac{z^2}{c^2} = 1$	$x = a\sqrt{1+r^2} \cos \theta \quad y = b\sqrt{1+r^2} \sin \theta \quad z = cr$ $0 \leq r < \infty, 0 < \theta < 2\pi$


Hyperboloid of Two Sheets

Image	Cartesian Form	Cylindrical Parameterization
	$\frac{z^2}{c^2} - \frac{x^2}{a^2} - \frac{y^2}{b^2} = 1$	$x = a\sqrt{r^2-1} \cos \theta \quad y = b\sqrt{r^2-1} \sin \theta \quad z = cr$ $0 \leq r < \infty, 0 < \theta < 2\pi$


Elliptic Paraboloid

Image	Cartesian Form	Cylindrical Parameterization
	$z = \frac{x^2}{a^2} + \frac{y^2}{b^2}$	$x = \sqrt{ar} \cos \theta \quad y = \sqrt{br} \sin \theta \quad z = r$ $0 \leq r < \infty, 0 < \theta < 2\pi$

Hyperbolic Paraboloid

Image	Cartesian Form	Cylindrical Parameterization
	$z = \frac{x^2}{a^2} - \frac{y^2}{b^2}$	$x = ar \cos \theta \quad y = -br \sin \theta \quad z = r^2(\cos^2 \theta - \sin^2 \theta)$ $0 \leq r < \infty, 0 < \theta < 2\pi$

Cylinder

Image	Cartesian Form	Cylindrical Parameterization	Spherical Parameterization
	$(x - h)^2 + (y - k)^2 = r^2$	$x = h + r \cos \theta \quad y = k + r \sin \theta$ $z = r \quad r \text{ is constant, } 0 < \theta < 2\pi$	(centered at origin without h and k) $\rho = r \csc \phi \quad x = r \cos \theta \quad y = r \sin \theta$ $z = r \cos \theta \quad 0 < \theta < 2\pi \quad 0 < \rho < \pi$